

# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## September / October 2023 Supplementary Examinations

**Programme: B.E.**

**Branch: Aerospace Engineering**

**Course Code: 20AE6DCDSM**

**Course: Flight Dynamics and Space Mechanics**

**Semester: VI**

**Duration: 3 hrs.**

**Max Marks: 100**

**Date: 27.09.2023**

**Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

### UNIT - I

- 1 a) Write down the accepted limits on Euler angles. Convert the co-ordinate of the position vector in the earth axis system defined by

$$\vec{F}_E = x_E \hat{i}_E + y_E \hat{j}_E + z_E \hat{k}_E$$

to body axis system ( $\vec{F}_B$ ) based on the accepted sequence of Euler angles with possible vector diagrams.

- b) Derive the three moment equations of motion (with necessary assumptions) in body axis system of an aircraft starting from the angular momentum equation  $\vec{H} = I \vec{\omega}$ , where I is the Inertia tensor and  $\omega$  is the angular velocity.

### UNIT - II

- 2 a) Show that the derivative due to the changes in the forward speed (in x-direction with respect to  $u/U_1$ ) is dependent on the speed damping derivative and the co-efficient of aerodynamic drag under steady state condition.

- b) Find the  $u/U_1$  derivative for the F-4C aircraft at 10,500 m and Mach 0.9 ( $U_1 = 267$  m/s,  $q = 13,560$  N/m<sup>2</sup>,  $S = 50$  m<sup>2</sup>) if  $C_{D_1} = 0.03$  and  $C_{D_u} = 0.027$ . If U is perturbed to 268 m/s, find the perturbed applied aero force along the x stability axis ( $f_{A_x}$ ).

- c) Show that the derivative due to the changes in the forward speed (in x-direction with respect to  $u/U_1$ ) is dependent on the Mach-Tuck derivative and the co-efficient of moment under steady state condition.

**Important Note:** Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

## OR

- 3 a) Show that the derivative due to the change of angle of attack (in z-direction with respect to  $\hat{\alpha}$ ) is dependent on the lift-curve slope and the co-efficient of aerodynamic drag under steady state condition. 10
- b) Find the  $\hat{\alpha}$  derivative  $\frac{\partial F_{Az}}{\partial \hat{\alpha}}$  for the F-4C aircraft at the flight conditions at 10,500 m and Mach 0.9 ( $U_1 = 267$  m/s,  $q = 13,560$  N/m<sup>2</sup>,  $S = 50$  m<sup>2</sup>) if  $C_{D_1} = 0.03$  and  $C_{D_u} = 0.027$  in which  $C_{L_\alpha} = 3.75$  /rad. If the F-4C is trimmed at an angle of attack of  $2.6^\circ$  and then is perturbed to  $3.1^\circ$ , find the perturbed aero force along the z-stability axis ( $F_{Az}$ ). 10

## UNIT - III

- 4 a) Find the natural frequency and the damping ratio based on two degree of freedom Phugoid approximation is given by the standard equation given below. 12

$$\begin{bmatrix} s - X_u - X_{T_u} & -X_\alpha & g \cos \Theta_1 \\ -Z_u & [s(U_1 - Z_{\dot{\alpha}}) - Z_\alpha] & [-(Z_q + U_1)s + g \sin \Theta_1] \\ -(M_u - M_{T_u}) & -(M_{\dot{\alpha}}s + M_\alpha + M_{T_\alpha}) & (s^2 - M_q s) \end{bmatrix} \begin{bmatrix} U(s) \\ \alpha(s) \\ \theta(s) \end{bmatrix} = \begin{bmatrix} X_{\delta_e} \\ Z_{\delta_e} \\ M_{\delta_e} \end{bmatrix} \delta_e s$$

- b) The following is the longitudinal characteristic equation for an F-89 Scorpion flying at 6,096 m at Mach 0.638. Determine the short period and phugoid natural frequencies and also the damping ratios and damped frequencies for both modes: 8

$$(s^2 + 4.2102s + 18.2329)(s^2 + 0.00899s + 0.003969) = 0$$

## UNIT - IV

- 5 a) Describe the peculiarities of space environment. 10
- b) Describe the effect of space environment on materials of spacecraft structure and astronauts. 10

## UNIT - V

- 6 a) Prove that  $r_o = \frac{L^2}{GMm^2}$  and  $e^2 = 1 + \frac{2Er_o}{GMm}$  in an ellipse. Where  $r_o$  is the semi-latus rectum. 10
- b) An earth satellite is in an orbit with perigee altitude  $z_p = 400$  km and an eccentricity  $e = 0.6$ . Find (i) the perigee velocity (ii) the apogee radius (iii) the semimajor axis (iv) the apogee velocity (v) the period of the orbit. ( $\mu = 3,98,600$  km<sup>3</sup>/s<sup>2</sup> and the radius of the earth  $R = 6378$  km) 10

OR

- 7 a) Calculate the velocity and the orbiting time period of an artificial satellite having a circular orbit around the Earth at an altitude of 200 km above the Earth's surface. (Radius of the earth  $R = 6,378.14$  km and  $\mu = 398600.5$  km<sup>3</sup>/s<sup>2</sup>). 5
- b) In an inertial coordinate system, the position and velocity vectors of a satellite are, respectively,  $(1.2756 \vec{i} + 1.9135 \vec{j} + 3.1891 \vec{k}) 10^7$  m and  $(0.7905 \vec{i} + 1.5811 \vec{j}) 10^4$  m/s where  $\vec{i}$ ,  $\vec{j}$  and  $\vec{k}$  are unit vectors. Determine the specific mechanical energy ( $\xi$ ) and the specific angular momentum (h) Also find the flight path angle,  $\phi$ . (Take  $G = 6.67 \times 10^{-11}$  m<sup>3</sup> kg<sup>-1</sup>s<sup>-2</sup> and  $\mu = 398600.5$  km<sup>3</sup>/s<sup>2</sup>). 10
- c) State and derive Kepler's third law of planetary motion. 5

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