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# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## September / October 2023 Supplementary Examinations

**Programme: B.E.**

**Branch: Artificial Intelligence And Machine Learning**

**Course Code: 22AM6PCDEL**

**Course: Deep Learning**

**Semester: VI**

**Duration: 3 hrs.**

**Max Marks: 100**

**Date: 14.09.2023**

**Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

### UNIT - I

1 a) Differentiate between  $L^1$  and  $L^2$  regularizations in detail. In which scenarios are these regularizations best suited? **10**

b) Design a Neural Network Model to solve the following Truth Table with a sigmoidal activation function: **05**

| <b>X1</b> | <b>X2</b> | <b>Y</b> |
|-----------|-----------|----------|
| 0         | 0         | 0        |
| 0         | 1         | 1        |
| 1         | 0         | 1        |
| 1         | 1         | 0        |

c) Justify why the Softmax units are best suitable for a Multinoulli Output Distribution environment. **05**

### OR

2 a) With suitable algorithmic steps, illustrate the forward propagation and backward computation algorithms of a Deep Neural Network in detail. **10**

b) Is Dropout a computationally inexpensive and yet a powerful method for regularization? Explain. **10**

### UNIT - II

3 a) Elaborate on the possible challenges that could be faced while training a Recurrent Neural Network(RNN). **10**

**Important Note:** Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

b) For training a sequence prediction task using RNN, given a training dataset with 1000 sequences, each consisting of 20-time steps and 5 features, with a mini-batch size of 32, how many iterations would be required to complete one epoch of training? Construct the relevant architectural block and conclude the solution accordingly. 10

### **UNIT – III**

4 a) Elaborate on the concepts of activation layer and pooling of a Convolutional Neural Network (CNN) along with suitable numerical examples. 12

b) Design a CNN model with the following layers and determine the number of parameters in it: 08

Input: Grayscale images of size 128x128 pixels

Convolutional layer 1: 32 filters of size 3x3, stride 1, and padding of 1

Convolutional layer 2: 64 filters of size 3x3, stride 1, and padding of 1

Convolutional layer 3: 128 filters of size 3x3, stride 1, and padding of 1

Global average pooling layer: Pool over the spatial dimensions

Fully connected layer 1: 256 neurons

Output layer: Number of medical conditions/classes

### **UNIT - IV**

5 a) Illustrate the application of Greedy layer-wise unsupervised pertaining protocol in a representation learning environment along with its algorithm. 10

b) Prove that the Transfer Learning between 2 domains enable Zero-Shot learning along with necessary mathematical models and diagrammatic representations. 10

### **UNIT - V**

6 a) Explain the Differentiable Generator Networks by deriving necessary mathematical relations. 10

b) Derive the conditional distribution property of a Restricted Boltzmann Machine (RBM) and elaborate the procedure briefly. 10

### **OR**

7 a) Using process graphs, explain the Markov chain process model that is related with a trained denoising Autoencoder which will be used for generating samples from the probabilistic models. 10

b) How does the concept of Boltzmann machine support multi-prediction? Elaborate on the process of training such models with necessary relations and block diagrams. 10

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