

U.S.N.

# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## January / February 2025 Semester End Main Examinations

Programme: B.E.

Semester: VI

Branch: Artificial Intelligence and Machine Learning

Duration: 3 hrs.

Course Code: 24AM6PCDEL

Max Marks: 100

Course: Deep Learning

**Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

		UNIT - I	CO	PO	Marks												
1	a)	Illustrate how ReLU and tanh activation functions exhibit saturation.	CO2	PO2	06												
	b)	Consider a Deep Neural Network (DNN) with the following structure: <ul style="list-style-type: none"><li>Inputs to the hidden layer: <math>z = [0.8, 0.6, 0.7, 0.9]</math>.</li><li>Weight matrix connecting the hidden layer to the output layer:<table><tr><td>0.2</td><td>0.5</td><td>0.3</td><td>0.8</td></tr><tr><td>0.7</td><td>0.1</td><td>0.6</td><td>0.4</td></tr><tr><td>0.9</td><td>0.2</td><td>0.5</td><td>0.3</td></tr></table></li><li>Bias vector for the output layer: <math>[0.1, 0.3, 0.5]</math></li><li>Activation function at the hidden layer: ReLU</li><li>Activation function at the output layer: Softmax</li></ul> Compute the output probabilities for each class.	0.2	0.5	0.3	0.8	0.7	0.1	0.6	0.4	0.9	0.2	0.5	0.3	CO3	PO3	10
0.2	0.5	0.3	0.8														
0.7	0.1	0.6	0.4														
0.9	0.2	0.5	0.3														
	c)	Describe any two heuristics that can be used to accelerate the training process of a DNN.	CO1	PO1	04												
		OR															
2	a)	Describe the significance of injecting noise at the output targets	CO2	PO2	06												
	b)	Consider a binary classification problem where a neural network predicts whether an image contains a cat (class 1) or not (class 0). True labels are $y = [1, 0, 1, 1, 0]$ and the predicted probabilities for class 1 are $p = [0.9, 0.3, 0.8, 0.88, 0.1]$ . Apply cross-entropy loss function and compute the error between the predicted probabilities and the true labels.	CO3	PO3	10												
	c)	Explain the need of data augmentation.	CO1	PO1	04												
		UNIT - II															
3	a)	Write an early stopping meta-algorithm to determine the best amount of training time.	CO1	PO1	06												

	b)	How does gradient clipping help in addressing the exploding gradient problem?	CO1	PO1	07						
	c)	Consider a densely connected base network featuring two visible units, one hidden layer containing two hidden units, and a single output unit. Illustrate the base network and depict all possible sub-networks that can be generated by dropping out various subsets of units from the base network.	CO2	PO2	07						
		OR									
4	a)	Explain parameter tying and parameter sharing using a suitable application.	CO1	PO1	06						
	b)	Differentiate RMSProp and RMSProp with Nesterov momentum.	CO1	PO1	06						
	c)	Explain the use of early stopping as a meta-algorithm to i. Identify the onset of overfitting during training. ii. Determine the optimal number of training steps for retraining on the full dataset.	CO1	PO1	08						
		UNIT - III									
5	a)	Using suitable mathematical equations differentiate between Long Short Term Memory (LSTM) and Gated Recurrent Units (GRUs).	CO1	PO1	06						
	b)	Compute the values of input gate and output gate of a LSTM cell by considering the given data <table><tr><td>Weights for the input gate <math>W_i = \begin{bmatrix} 0.5 &amp; 0.4 \\ 0.3 &amp; 0.2 \end{bmatrix}</math> Hidden state <math>h_{t-1} = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}</math></td><td>Recurrent weights for the input gate <math>U_i = \begin{bmatrix} 0.1 &amp; 0.2 \\ 0.3 &amp; 0.4 \end{bmatrix}</math> Biases for the input gate <math>b_i = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}</math></td></tr><tr><td>Input vector <math>x_t = \begin{bmatrix} 0.5 \\ 0.6 \end{bmatrix}</math></td><td>Weights for the output gate <math>W_o = \begin{bmatrix} 0.7 &amp; 0.6 \\ 0.5 &amp; 0.4 \end{bmatrix}</math></td></tr><tr><td>Recurrent weights for the output gate <math>U_o = \begin{bmatrix} 0.3 &amp; 0.4 \\ 0.5 &amp; 0.6 \end{bmatrix}</math></td><td>Biases for the output gate <math>b_o = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}</math></td></tr></table>	Weights for the input gate $W_i = \begin{bmatrix} 0.5 & 0.4 \\ 0.3 & 0.2 \end{bmatrix}$ Hidden state $h_{t-1} = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$	Recurrent weights for the input gate $U_i = \begin{bmatrix} 0.1 & 0.2 \\ 0.3 & 0.4 \end{bmatrix}$ Biases for the input gate $b_i = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$	Input vector $x_t = \begin{bmatrix} 0.5 \\ 0.6 \end{bmatrix}$	Weights for the output gate $W_o = \begin{bmatrix} 0.7 & 0.6 \\ 0.5 & 0.4 \end{bmatrix}$	Recurrent weights for the output gate $U_o = \begin{bmatrix} 0.3 & 0.4 \\ 0.5 & 0.6 \end{bmatrix}$	Biases for the output gate $b_o = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$	CO3	PO3	10
Weights for the input gate $W_i = \begin{bmatrix} 0.5 & 0.4 \\ 0.3 & 0.2 \end{bmatrix}$ Hidden state $h_{t-1} = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$	Recurrent weights for the input gate $U_i = \begin{bmatrix} 0.1 & 0.2 \\ 0.3 & 0.4 \end{bmatrix}$ Biases for the input gate $b_i = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$										
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Recurrent weights for the output gate $U_o = \begin{bmatrix} 0.3 & 0.4 \\ 0.5 & 0.6 \end{bmatrix}$	Biases for the output gate $b_o = \begin{bmatrix} 0.1 \\ 0.2 \end{bmatrix}$										
	c)	Explain the vanishing gradient problem in Recurrent Neural Network (RNN).	CO1	PO1	04						
		OR									
6	a)	How does Vanilla RNN differ from Bi-directional RNN?	CO2	PO2	06						
	b)	Compute the values of update gate and the Candidate Hidden State $\tilde{h}_t$ of a GRU cell by considering the given data <table><tr><td>Weights for the update gate <math>W_z = \begin{bmatrix} 0.1 &amp; 0.2 &amp; 0.3 &amp; 0.4 \\ 0.5 &amp; 0.6 &amp; 0.7 &amp; 0.8 \end{bmatrix}</math></td><td>Biases for the update gate <math>b_z = [0.1, 0.2]</math> Input vector</td></tr></table>	Weights for the update gate $W_z = \begin{bmatrix} 0.1 & 0.2 & 0.3 & 0.4 \\ 0.5 & 0.6 & 0.7 & 0.8 \end{bmatrix}$	Biases for the update gate $b_z = [0.1, 0.2]$ Input vector	CO3	PO3	10				
Weights for the update gate $W_z = \begin{bmatrix} 0.1 & 0.2 & 0.3 & 0.4 \\ 0.5 & 0.6 & 0.7 & 0.8 \end{bmatrix}$	Biases for the update gate $b_z = [0.1, 0.2]$ Input vector										

		<div>Previous hidden state <math>h_{t-1} = [0.1, 0.4]</math></div> <div>Candidate Activation <math>W_h = \begin{bmatrix} 0.1 &amp; 0.2 &amp; 0.3 &amp; 0.4 \\ 0.5 &amp; 0.6 &amp; 0.7 &amp; 0.8 \end{bmatrix}</math> <math>b_h = [0.1, 0.2]</math></div> <div><math>x_t = [0.5, -0.2]</math></div> <div>Reset Gate <math>r_t \approx \begin{bmatrix} 0.5646 \\ 0.6630 \end{bmatrix}</math></div>																							
	c)	Write the Back Propagation Through Time (BPTT) algorithm.	CO1	PO1	04																				
		UNIT - IV																							
7	a)	Consider a Convolutional Neural Network (CNN) with the following configuration: An input image of size 4x4: <table><tr><td>1</td><td>2</td><td>0</td><td>3</td></tr><tr><td>4</td><td>6</td><td>2</td><td>1</td></tr><tr><td>1</td><td>2</td><td>5</td><td>3</td></tr><tr><td>0</td><td>1</td><td>2</td><td>4</td></tr></table> A single 2x2 filter (kernel) with weights: <table><tr><td>0</td><td>1</td></tr><tr><td>-1</td><td>1</td></tr></table> <div>i. Perform convolution operation on the given input image using the specified filter and stride = 1. Write the resulting feature map.</div> <div>ii. Apply ReLU activation function to the result obtained in (i). Represent the updated feature map in the matrix form.</div> <div>iii. Perform max pooling on the feature map obtained from (ii) using 2*2 pooling window and stride = 1. Determine the resulting feature map.</div>	1	2	0	3	4	6	2	1	1	2	5	3	0	1	2	4	0	1	-1	1	CO3	PO3	10
1	2	0	3																						
4	6	2	1																						
1	2	5	3																						
0	1	2	4																						
0	1																								
-1	1																								
	b)	Is it possible to retain the original size of the image after the process of convolution? Justify with an example.	CO2	PO2	06																				
	c)	Elaborate on key application areas of adversarial training.	CO1	PO1	04																				
		OR																							
8	a)	Design a CNN with the following specification to classify images of handwritten digits between 0 and 9. Represent the size of the intermediate feature maps precisely on the architectural design. <div><div>Input: (28, 28, 1)</div><div>Conv1: 32 filters, kernel: 3x3, activation function: ReLU</div><div>Pool1: 2x2 Max Pooling</div><div>Conv2: 64 filters, kernel: 3x3, activation function: ReLU</div><div>Pool2: 2x2 Max Pooling</div><div>Flatten</div><div>Dense: 128 neurons, activation function: ReLU</div><div>Output: 10 neurons, activation function: Softmax</div></div>	CO3	PO3	10																				
	b)	Given an image of size 30*30 with 3*3 kernel, horizontal stride = 2 and vertical stride = 2. Calculate the size of the resultant feature map.	CO3	PO3	04																				

	c)	Can Manifold Tangent Classifier be used to improve the accuracy of classification? Justify.	CO2	PO2	06											
		UNIT - V														
9	a)	Explain process of training a Hopfield network along with relevant mathematical representations.	CO1	PO1	07											
	b)	Illustrate the steps of Contrastive divergence algorithm, for training Restricted Boltzmann Machine (RBM).	CO2	PO2	05											
	c)	Consider an RBM with 2 visible units and 2 hidden units. Given the weights and biases: Weight matrix $W = \begin{bmatrix} 0.5 & -0.7 \\ 0.2 & 0.3 \end{bmatrix}$ Visible unit biases $b_v$ : [0.1, -0.2]  Hidden unit biases $b_h$ : [0.3, 0.4]  Calculate the probabilities of the hidden units being activated given a specific visible vector $v=[1,0]$ .	CO3	PO3	08											
		OR														
10	a)	Illustrate the training process of multilayer Restricted Boltzmann Machines.	CO2	PO1	07											
	b)	Differentiate between Boltzman Machine and Restricted Boltzman Machine.	CO2	PO2	05											
	c)	A Restricted Boltzmann Machine (RBM) with 3 visible units and 2 hidden units has the following initial weights $W$ between the visible and hidden units: <table border="1"><tr><td>0.1</td><td>-0.2</td></tr><tr><td>0.4</td><td>0.5</td></tr><tr><td>-0.3</td><td>0.2</td></tr></table> The biases for the visible units and the hidden units are: <table border="1"><tr><td>0.1</td></tr><tr><td>0.2</td></tr><tr><td>-0.1</td></tr></table> <table border="1"><tr><td>0.1</td></tr><tr><td>-0.1</td></tr></table> Given an input vector $v = (1 \ 0 \ 1)$ and learning rate = 0.1 use sigmoid function and illustrate the process of weight updates using Contrastive Divergence algorithm for 1 epoch.	0.1	-0.2	0.4	0.5	-0.3	0.2	0.1	0.2	-0.1	0.1	-0.1	CO3	PO3	08
0.1	-0.2															
0.4	0.5															
-0.3	0.2															
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