

U.S.N.

# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## June 2025 Semester End Main Examinations

Programme: B.E.

Semester: III

Branch: Electronics &amp; Telecommunication Engineering

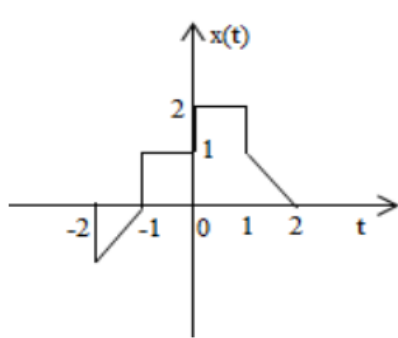
Duration: 3 hrs.

Course Code: 23ET3PCSSA

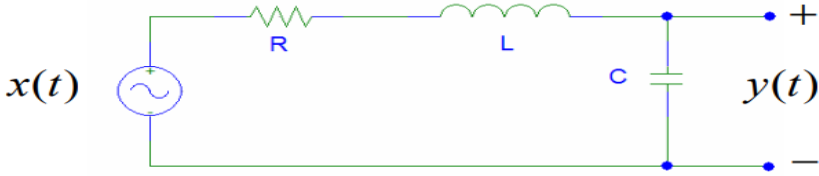
Max Marks: 100

Course: SIGNALS AND SYSTEMS: ANALOG

- Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.			<b>UNIT - I</b>	<b>CO</b>	<b>PO</b>	<b>Marks</b>
	1	a)	Classify the signals with an example each.	CO1		10
		b)	A continuous time signal $x(t)$ is shown in fig (1b).  <p>fig (1b)</p> sketch and label each of the following signal: i) $x(t-1)$ ii) $x(2-t)$ iii) $x(t)[\delta(t+3/2) - \delta(t-3/2)]$ iv) $x(2t+1)$	CO2	PO1	10
			<b>OR</b>			
	2	a)	List the various operations performed on independent and dependent variables with an example.	CO1	-	10
		b)	Justify whether the following system are linear or nonlinear, time invariant or not, causal or noncausal, stable or unstable. (i) $y(t) = t x(t)$ (ii) $y(t) = x(t) u(t)$ .	CO2	PO2	10
			<b>UNIT - II</b>			
	3	a)	List the basic properties of convolution integral with example.	CO2	PO1	04
		b)	Consider two continuous signals $x(t) = e^{-3t} [u(t) - u(t-2)]$ and $h(t) = e^{-t} u(t)$ ;	CO2	PO1	08

		(i) Evaluate $y(t)$ using convolution integral (ii) Check $h(t)$ is causal or not.			
	c)	The impulse response of a continuous-time LTI system is given by: $h(t)=e^{-t}u(t+1)$ Analyze if the system is causal and explain its stability characteristics.	CO2	PO2	08
		<b>OR</b>			
4	a)	List the difference between auto correlation and Cross correlation.	CO2	PO1	04
	b)	Perform the convolution operation of the following signals $x_1(t)=e^{- t-2 }$ and $x_2(t)=e^{-2t}u(t+4)$ and plot the output	CO2	PO1	08
	c)	The input $x(t)$ and impulse response $h(t)$ of a continuous time LTI system as $x(t)=u(t)$ and $h(t)=e^{-at}u(t)$ . Compute the output $y(t)$	CO2	PO2	08
		<b>UNIT - III</b>			
5	a)	Show how to compute the Fourier Transform of a periodic signal using its Fourier series coefficients.	CO3	PO1	05
	b)	Compute the Fourier series coefficients for the periodic square wave given by: $x(t) = \begin{cases} A, & 0 \leq t < T/2, \\ -A, & T/2 \leq t < T, \end{cases}$ where $T$ is the period of the signal.	CO3	PO1	08
	c)	Verify the Parseval's theorem for the signal $x(t)=e^{-t}u(t)$ .	CO3	PO2	07
		<b>OR</b>			
6	a)	Define the magnitude spectrum and phase spectrum of a signal. Explain their significance in analyzing signals.	CO3	PO1	05
	b)	Determine the magnitude and phase spectrum of the signal $x(t)=e^{-2 t }$	CO3	PO1	08
	c)	Find Power spectral density of unit step function.	CO3	PO2	07
		<b>UNIT - IV</b>			
7	a)	For the transfer function, $H(s) = \frac{1}{s^2+2s+5}$ plot the poles and zeros and comment on the damping and oscillatory nature of the system.	CO3	PO2	07

		b)	Derive the transfer function $H(s)$ of a system whose input-output relationship is governed by the differential equation:  $\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = 3x(t)$	CO3	PO1	05
		c)	For the transfer function, $H(s) = \frac{1}{s+2}$ determine its magnitude and phase response. Plot the frequency response.	CO3	PO2	08
			OR			
	8	a)	Find Transfer function of 	CO3	PO2	07
		b)	Explain the concept of block diagram representation of systems with respect to direct form-I and direct from-II.	CO3	PO1	05
		c)	Solve the differential equation $\frac{dy(t)}{dt} + 3y(t) = 2x(t)$ for $x(t) = e^{-t}u(t)$ using the Laplace Transform.	CO3	PO2	08
			UNIT - V			
	9	a)	Why the Butterworth filter referred to as a "maximally flat" filter? Provide a brief explanation.	CO4	PO1	04
		b)	Given the attenuation requirements for a Butterworth filter at $f_p=3$ kHz (passband) and $f_s=15$ kHz (stopband), with $A_p=1$ dB and $A_s=45$ dB, calculate the minimum order of the filter.	CO4	PO3	08
		c)	Design a first-order Butterworth high-pass filter with a cutoff frequency of 1 kHz. Specify the component values.	CO4	PO3	08
			OR			
	10	a)	Explain practical implementation of first order Butterworth Low pass filter.	CO4	PO1	04
		b)	A low-pass Butterworth filter has the following specifications: <ul style="list-style-type: none"> <li>Cutoff frequency: <math>f_c=2</math> kHz</li> </ul>	CO4	PO3	08

			<ul style="list-style-type: none"> <li>Passband ripple: <math>A_p=1</math> dB,</li> <li>Stopband attenuation: <math>A_s=40</math> dB at <math>f_s=16</math> kHz</li> </ul> <p>Calculate the order of the filter and sketch the approximate magnitude response.</p>			
		c)	Design a first order Butterworth low-pass filter with a cutoff frequency of 2 kHz. Specify the component values.	CO4	PO3	<b>08</b>

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REAPPEAR EXAMS 2024-25