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# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## June 2025 Semester End Main Examinations

**Programme: B.E.**

**Semester: III**

**Branch: Electronics & Telecommunication Engineering**

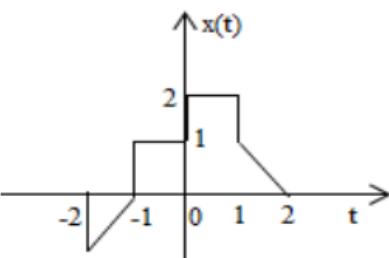
**Duration: 3 hrs.**

**Course Code: 23ET3PCSSA**

**Max Marks: 100**

**Course: SIGNALS AND SYSTEMS: ANALOG**

**Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

UNIT - I			CO	PO	Marks
1	a)	Classify the signals with an example each.	CO1		<b>10</b>
	b)	A continuous time signal $x(t)$ is shown in fig (1b).	CO2	PO1	<b>10</b>
 <p>fig (1b)</p> <p>sketch and label each of the following signal:</p> <p>i) <math>x(t-1)</math>      ii) <math>x(2-t)</math>      iii) <math>x(t)[\delta(t+3/2) - \delta(t-3/2)]</math>  iv) <math>x(2t+1)</math></p>					
<b>OR</b>					
2	a)	List the various operations performed on independent and dependent variables with an example.	CO1	-	<b>10</b>
	b)	Justify whether the following system are linear or nonlinear, time invariant or not, causal or noncausal, stable or unstable. (i) $y(t) = t x(t)$ (ii) $y(t) = x(t) u(t)$ .	CO2	PO2	<b>10</b>
UNIT - II					
3	a)	List the basic properties of convolution integral with example.	CO2	PO1	<b>04</b>
	b)	Consider two continuous signals $x(t) = e^{-3t}[u(t) - u(t-2)]$ and $h(t) = e^{-t}u(t)$ ;	CO2	PO1	<b>08</b>

**Important Note:** Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

		(i) Evaluate $y(t)$ using convolution integral (ii) Check $h(t)$ is causal or not.			
	c)	The impulse response of a continuous-time LTI system is given by: $h(t)=e^{-t}u(t+1)$ Analyze if the system is causal and explain its stability characteristics.	CO2	PO2	<b>08</b>
		<b>OR</b>			
4	a)	List the difference between auto correlation and Cross correlation.	CO2	PO1	<b>04</b>
	b)	Perform the convolution operation of the following signals $x_1(t)=e^{- t-2 }$ and $x_2(t)=e^{-2t}u(t+4)$ and plot the output	CO2	PO1	<b>08</b>
	c)	The input $x(t)$ and impulse response $h(t)$ of a continuous time LTI system as $x(t)=u(t)$ and $h(t)=e^{-at}u(t)$ . Compute the output $y(t)$	CO2	PO2	<b>08</b>
		<b>UNIT - III</b>			
5	a)	Show how to compute the Fourier Transform of a periodic signal using its Fourier series coefficients.	CO3	PO1	<b>05</b>
	b)	Compute the Fourier series coefficients for the periodic square wave given by: $x(t) = \begin{cases} A, & 0 \leq t < T/2, \\ -A, & T/2 \leq t < T, \end{cases}$ where $T$ is the period of the signal.	CO3	PO1	<b>08</b>
	c)	Verify the Parseval's theorem for the signal $x(t)=e^{-t}u(t)$ .	CO3	PO2	<b>07</b>
		<b>OR</b>			
6	a)	Define the magnitude spectrum and phase spectrum of a signal. Explain their significance in analyzing signals.	CO3	PO1	<b>05</b>
	b)	Determine the magnitude and phase spectrum of the signal $x(t)=e^{-2 t }$	CO3	PO1	<b>08</b>
	c)	Find Power spectral density of unit step function.	CO3	PO2	<b>07</b>
		<b>UNIT - IV</b>			
7	a)	For the transfer function, $H(s) = \frac{1}{s^2+2s+5}$ plot the poles and zeros and comment on the damping and oscillatory nature of the system.	CO3	PO2	<b>07</b>

	b)	Derive the transfer function $H(s)$ of a system whose input-output relationship is governed by the differential equation:  $\frac{d^2y(t)}{dt^2} + 5\frac{dy(t)}{dt} + 6y(t) = 3x(t)$	CO3	PO1	<b>05</b>
	c)	For the transfer function,  $H(s) = \frac{1}{s+2}$  determine its magnitude and phase response. Plot the frequency response.	CO3	PO2	<b>08</b>
		<b>OR</b>			
8	a)	Find Transfer function of  	CO3	PO2	<b>07</b>
	b)	Explain the concept of block diagram representation of systems with respect to direct form-I and direct form-II.	CO3	PO1	<b>05</b>
	c)	Solve the differential equation  $\frac{dy(t)}{dt} + 3y(t) = 2x(t) \text{ for } x(t) = e^{-t}u(t)$ using the Laplace Transform.	CO3	PO2	<b>08</b>
		<b>UNIT - V</b>			
9	a)	Why the Butterworth filter referred to as a "maximally flat" filter? Provide a brief explanation.	CO4	PO1	<b>04</b>
	b)	Given the attenuation requirements for a Butterworth filter at $f_p=3$ kHz (passband) and $f_s=15$ kHz (stopband), with $A_p=1$ dB and $A_s=45$ dB, calculate the minimum order of the filter.	CO4	PO3	<b>08</b>
	c)	Design a first-order Butterworth high-pass filter with a cutoff frequency of 1 kHz. Specify the component values.	CO4	PO3	<b>08</b>
		<b>OR</b>			
10	a)	Explain practical implementation of first order Butterworth Low pass filter.	CO4	PO1	<b>04</b>
	b)	A low-pass Butterworth filter has the following specifications: <ul style="list-style-type: none"> <li>Cutoff frequency: <math>f_c=2</math> kHz</li> </ul>	CO4	PO3	<b>08</b>

		<ul style="list-style-type: none"> <li>Passband ripple: <math>A_p=1</math> dB,</li> <li>Stopband attenuation: <math>A_s=40</math> dB at <math>f_s=16</math> kHz Calculate the order of the filter and sketch the approximate magnitude response.</li> </ul>			
	c)	Design a first order Butterworth low-pass filter with a cutoff frequency of 2 kHz. Specify the component values.	CO4	PO3	<b>08</b>

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REAPPEAR EXAMS 2024-25