

U.S.N.								
--------	--	--	--	--	--	--	--	--

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

October 2023 Semester End Main Examinations

Programme: B.E.

Semester: IV

Branch: ECE, ETE, EEE, MD, EIE

Duration: 3 hrs.

Course Code: 19ES4ESCST

Max Marks: 100

Course: Control Systems

Instructions: 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

UNIT - I

1 a) Enumerate the important features of feedback control systems. Explain with an example. **08**

b) Apply the fundamental laws to obtain the mathematical model translational mechanical system shown in fig 1b. Also obtain the F-V and F-I analogy. **12**

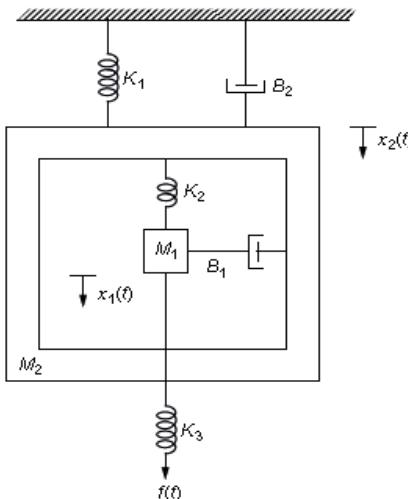


fig 1b

OR

2 a) Enumerate the differences between open and closed loop control system. **05**

b) Apply the appropriate reduction rules and obtain the transfer function for the system shown in Figure 2(b). **08**

Important Note: Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

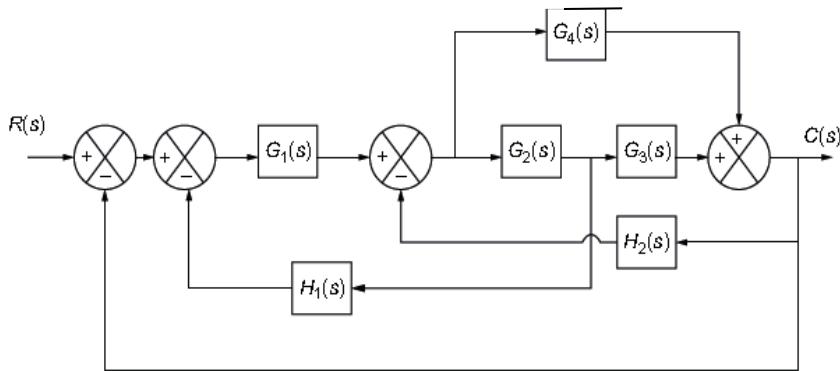


Fig. 2(b)

c) Apply Mason Gain Formula to obtain transfer function for the system shown in Figure 2(b). 07

UNIT - II

3 a) Define the time domain specifications of a second order system injected with a unit step input with diagram. 06

b) A feedback system has $G(s) = \frac{144}{s(s+2)}$, $H(s) = 1$ Determine the time-domain specifications such as rise time, percentage peak overshoot, peak time and settling time when the system is subjected to a step input of 1 unit. 08

c) The open-loop transfer function of a unity feedback system is $G(s) = \frac{k}{s(1+0.025s)}$ and damping ratio = 0.4. Determine K and the steady-state error for the ramp input. 06

UNIT - III

4 a) The characteristic equation of a single loop feedback system is given as 10
 i) $F(s) = s^6 + 3s^5 + 5s^4 + 9s^3 + 8s^2 + 3s + k = 0$
 ii) $F(s) = s^4 + 3s^3 + 3ks^2 + (k+2)s + 4 = 0$
 Find the stability of the system using R-H criterion and the range of value of k for stability if applicable.

b) Sketch the root locus of the system whose loop transfer function is given by $G(s)H(s) = \frac{K}{s(s^2+2s+2)}$. Comment on the stability of the system. 10

UNIT - IV

5 a) Explain the stability analysis using polar plot. 06
 b) Comment on stability using Nyquist criterion for the system having $G(s)H(s) = \frac{50}{s(1+s)(2+s)}$ 09
 c) Obtain the polar plot for $G(s)H(s) = \frac{1}{s^2(1+s)}$ 05

OR

6 a) Define the frequency domain specifications. 06
 b) Sketch the Bode plot and determine the frequency domain specifications for $G(s)H(s) = \frac{80}{(s+2)(s+20)}$ Also, comment on the stability of the system. 14

UNIT - V

7 a) Determine the state-space model for the electrical system shown in Fig. 7(a)

08

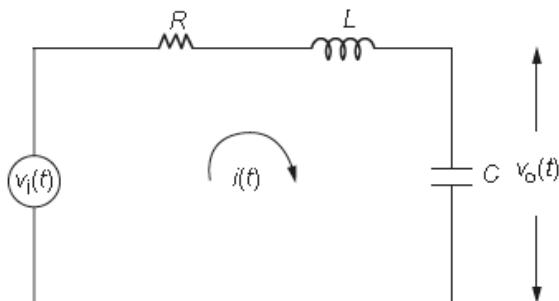


Fig. 7(a)

b) Obtain state-space representation for the system represented by

$$\frac{d^3y(t)}{dt^3} + 8\frac{d^2y(t)}{dt^2} + 11\frac{dy(t)}{dt} + 6y(t) = u(t)$$

c) Obtain the transfer function for the state-space representation of a system given

06

by

$$A = [-1 \ -2 \ 3; 0 \ -1 \ 1; -3 \ -1 \ -1]; B = [0; 0; 1]; C = [0 \ 1 \ 0]; D = [0 \ 0 \ 0]$$
