

B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

October 2023 Semester End Main Examinations

Programme: B.E.

Branch: ECE,ETE,EEE,MD,EIE

Course Code: 19ES4ESCST

Course: Control Systems

Semester: IV

Duration: 3 hrs.

Max Marks: 100

- Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.
2. Missing data, if any, may be suitably assumed.

UNIT - I

- 1 a) Enumerate the important features of feedback control systems. Explain with an example. **08**
- b) Apply the fundamental laws to obtain the mathematical model translational mechanical system shown in fig 1b. Also obtain the F-V and F-I analogy. **12**

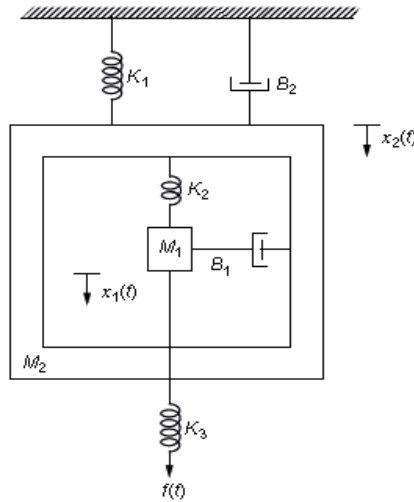


fig 1b

OR

- 2 a) Enumerate the differences between open and closed loop control system. **05**
- b) Apply the appropriate reduction rules and obtain the transfer function for the system shown in Figure 2(b). **08**

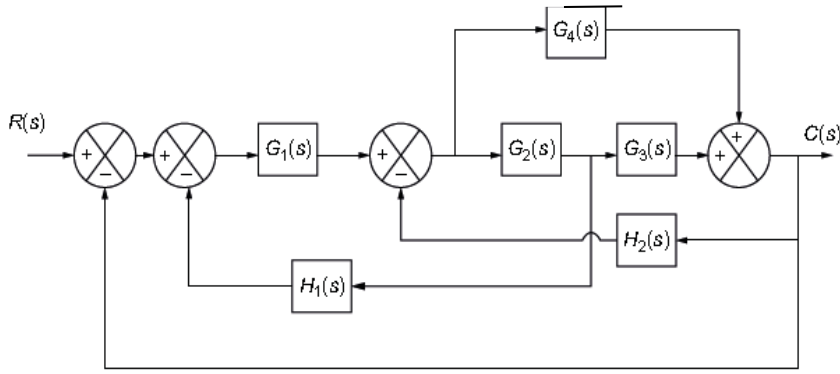


Fig. 2(b)

- c) Apply Mason Gain Formula to obtain transfer function for the system shown in Figure 2(b). 07

UNIT - II

- 3 a) Define the time domain specifications of a second order system injected with a unit step input with diagram. 06
- b) A feedback system has $G(s) = \frac{144}{s(s+2)}$, $H(s) = 1$ Determine the time-domain specifications such as rise time, percentage peak overshoot, peak time and settling time when the system is subjected to a step input of 1 unit. 08
- c) The open-loop transfer function of a unity feedback system is $G(s) = \frac{k}{s(1+0.025s)}$ and damping ratio = 0.4. Determine K and the steady-state error for the ramp input. 06

UNIT - III

- 4 a) The characteristic equation of a single loop feedback system is given as 10
- i) $F(s) = s^6 + 3s^5 + 5s^4 + 9s^3 + 8s^2 + 3s + k = 0$
- ii) $F(s) = s^4 + 3s^3 + 3ks^2 + (k+2)s + 4 = 0$
- Find the stability of the system using R-H criterion and the range of value of k for stability if applicable.
- b) Sketch the root locus of the system whose loop transfer function is given by $G(s)H(s) = \frac{K}{s(s^2+2s+2)}$. Comment on the stability of the system. 10

UNIT - IV

- 5 a) Explain the stability analysis using polar plot. 06
- b) Comment on stability using Nyquist criterion for the system having $G(s)H(s) = \frac{50}{s(1+s)(2+s)}$ 09
- c) Obtain the polar plot for $G(s)H(s) = \frac{1}{s^2(1+s)}$ 05

OR

- 6 a) Define the frequency domain specifications. 06
- b) Sketch the Bode plot and determine the frequency domain specifications for $G(s)H(s) = \frac{80}{(s+2)(s+20)}$ Also, comment on the stability of the system. 14

UNIT - V

- 7 a) Determine the state-space model for the electrical system shown in Fig. 7(a)

08

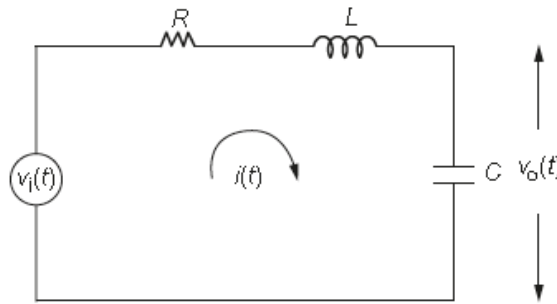


Fig. 7(a)

- b) Obtain state-space representation for the system represented by

06

$$\frac{d^3 y(t)}{dt^3} + 8 \frac{d^2 y(t)}{dt^2} + 11 \frac{dy(t)}{dt} + 6y(t) = u(t)$$

- c) Obtain the transfer function for the state-space representation of a system given by

06

$$A = \begin{bmatrix} -1 & -2 & 3 \\ 0 & -1 & 1 \\ -3 & -1 & -1 \end{bmatrix}; B = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}; C = \begin{bmatrix} 0 & 1 & 0 \end{bmatrix}; D = \begin{bmatrix} 0 & 0 & 0 \end{bmatrix}$$
