

# B.M.S. College of Engineering, Bengaluru-560019

Autonomous Institute Affiliated to VTU

## September / October 2023 Supplementary Examinations

**Programme: B.E.**

**Branch: Medical Electronics Engineering**

**Course Code: 19ML4PCPCS**

**Course: Physiological Control Systems**

**Semester: IV**

**Duration: 3 hrs.**

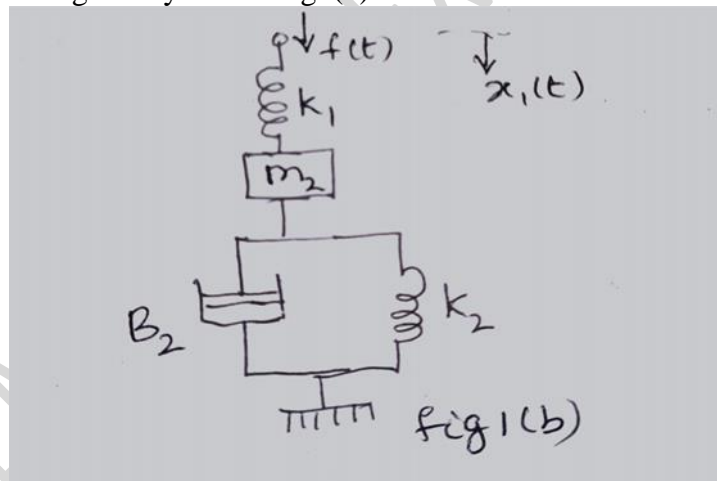
**Max Marks: 100**

**Date: 15.09.2023**

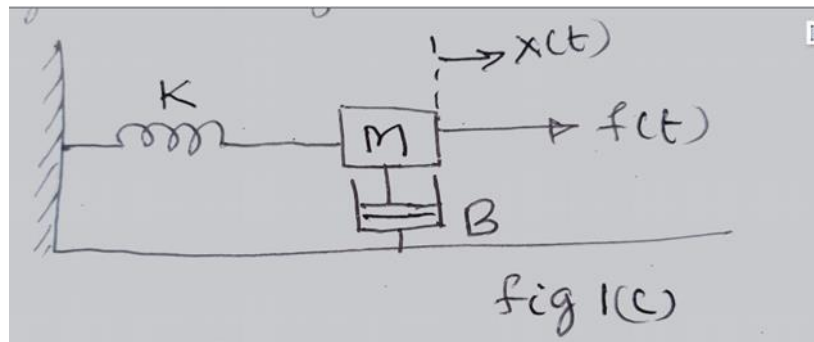
**Instructions:** 1. Answer any FIVE full questions, choosing one full question from each unit.  
2. Missing data, if any, may be suitably assumed.

### UNIT - I

- 1 a) Differentiate between open loop and closed control system with relevant examples. **06**
- b) Draw the equivalent mechanical system and analogous system based on F-V methods for the given system in fig1(b). **10**



- c) Obtain the equilibrium equation for the given system in fig1(c) **04**

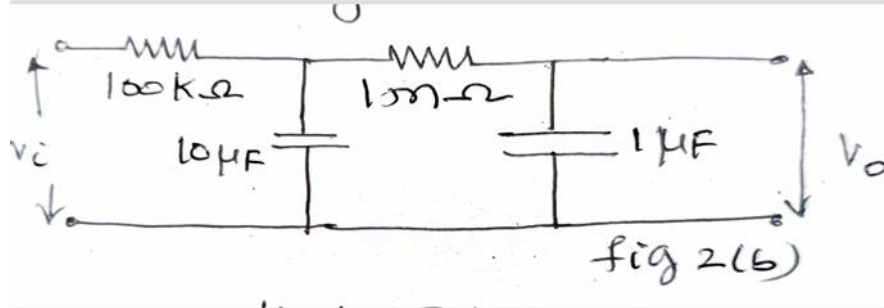


**OR**

- 2 a) Illustrate the working of muscle stretch reflex with a neat schematic diagram. **10**

**Important Note:** Completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Revealing of identification, appeal to evaluator will be treated as malpractice.

- b) For the system shown in fig 2(b), draw the signal flow graph and obtain the transfer function using Mason's rule. **10**



### UNIT - II

- 3 a) Derive an expression for the underdamped response of second order feed back control system for step input. **08**
- b) With a neat schematic explain the process involved in the regulation of glucose and insulin. **08**
- c) Derive the expression for (i) Rise time (ii) Peak overshoot of the second order feedback system with unity gain. **04**

### UNIT - III

- 4 a) The open loop transfer function of a unity feed back system is given by  $G(S) = K/S(1+ST_1)(1+ST_2)$ . Derive an expression for the gain K in terms of  $T_1$  and  $T_2$  for the stability of the system **06**
- b) Sketch the complete root locus for the system having  $G(S)H(S) = K/S(S+3)(S^2+3S+4.5)$  **14**

### UNIT - IV

- 5 a) Illustrate with schematic diagram, the process of starling Heart-Lung preparation. **08**
- b) Discuss with relevant equations minimal model of blood glucose regulation. **08**
- c) Brief about closed loop identification of the respiratory control system. **04**

### UNIT - V

- 6 a) For a particular unity feed back system  $G(S) = 242(S+5)/S(S+1)(S^2+5S+121)$  Sketch the bode plot, find  $\omega_{gc}$ ,  $\omega_{pc}$  G.M and PM comment on stability. **12**
- b) Define the following terms with respect to Bode plots. **08**
- (i) Gain Margin (G M)
  - (ii) Phase Margin (P M)
  - (iii) Gain cross over frequency
  - (iv) Phase cross over frequency.

### OR

- 7 a) Discuss the frequency response of Glucose-Insulin Regulation. **08**
- b) Discuss the Bode plot of frequency response of the Linearized Lung mechanics. **08**
- c) List and define the frequency domain specification. **04**

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